

*With the Author's Compliments.*

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Trajectories in the Irreversible Field of Force  
on the Surface.

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## Trajectories in the Irreversible Field of Force on a Surface,

by

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Consider a dynamical system with two degrees of freedom which is reduced to the normal form <sup>(1)</sup>:

$$(1) \quad \begin{aligned} \ddot{p} + \lambda \dot{q} &= \frac{\partial \gamma}{\partial p}, \\ \ddot{q} - \lambda \dot{p} &= \frac{\partial \gamma}{\partial q}, \end{aligned}$$

where  $p$  and  $q$  denote the two coordinates of the dynamical system,  $\dot{p}$  and  $\dot{q}$  their time derivatives, and  $\lambda, \gamma$  are functions of  $p$  and  $q$ . Then equations (1) admit the first integral

$$(2) \quad \frac{1}{2}(\dot{p}^2 + \dot{q}^2) = \gamma + h,$$

$h$  being an arbitrary constant.

Throughout this paper I will consider the motion of a particle on a surface and confine myself to the case in which  $h$  has a definite value. A few properties of the trajectories have been obtained in my previous paper <sup>(2)</sup>; but in the present I will deal with certain properties of a different nature, some of which may be considered as generalizations of those for the conservative field (that is, for the reversible field) <sup>(3)</sup>.

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<sup>(1)</sup> Birkhoff, "Dynamical systems with two degrees of freedom," Trans. Amer. Math. Soc., 18 (1917), p. 204.

<sup>(2)</sup> Ogura, "On a certain system of doubly infinite curves on a surface," Tôhoku Math. Journal, 8 (1915), p. 213; "A remark on the dynamical system with two degrees of freedom," Tôhoku Math. Journal, 15 (1919), p. 181. Hereafter these papers will be referred to as  $O_1$  and  $O_2$  respectively.

<sup>(3)</sup> Ogura, "Trajectories in the conservative field of force," Part I, Tôhoku Math. Journal, 7 (1915), p. 123; Part II, Tôhoku Math. Journal, 9 (1916), p. 134; "On the striped net of curves without ambages in dynamics," Proc. Tôkyô Math.-Phys. Soc., II 9 (1918), p. 284; "Note Supplementary to the paper 'on the striped net of curves without ambages in dynamics,'" Proc. Tôkyô Math.-Phys. Soc., II 9 (1918), p. 409. Hereafter these papers will be referred to as  $O_3, O_4, O_5, O_6$  respectively.



## PART I. General Theorems.

The condition for  $\infty^1$  given orbits.

1. Let the linear element of a surface  $S$  be

$$(3) \quad ds^2 = \mu (dp^2 + dq^2),$$

where isothermic parameters  $p$  and  $q$  are taken for parametrics. Then the differential equation of the orbits is <sup>(1)</sup>

$$(4) \quad q'' = \left( \frac{\partial \log \sqrt{\gamma+h}}{\partial q} - \frac{\partial \log \sqrt{\gamma+h}}{\partial p} q' \right) (1+q'^2) + \frac{\lambda}{\sqrt{2(\gamma+h)}} (1+q'^2)^{\frac{3}{2}},$$

where we have put

$$q' = \frac{dq}{dp}, \quad q'' = \frac{d^2q}{dp^2}.$$

Since  $\gamma+h$  and  $\mu$  are positive, we may put

$$\gamma+h = \frac{1}{2} \mu \varphi^2, \quad \frac{\lambda}{\sqrt{2(\gamma+h)}} = \sqrt{\mu} \psi;$$

so that (4) becomes

$$(5) \quad q'' = \left( \frac{\partial \log (\sqrt{\mu} \varphi)}{\partial q} - \frac{\partial \log (\sqrt{\mu} \varphi)}{\partial p} q' \right) (1+q'^2) + \sqrt{\mu} \psi (1+q'^2)^{\frac{3}{2}}.$$

The integral curves of this differential equation <sup>(2)</sup> will be called *the orbits in the field*  $(\varphi, \psi)$ .

Now suppose that

$$f(p, q) = \text{const.}$$

form a family of  $\infty^1$  orbits in the field  $(\varphi, \psi)$ . Since

$$q' = - \left( \frac{\partial f}{\partial p} \right) \cdot \left( \frac{\partial f}{\partial q} \right)^{-1},$$

$$q'' = - \left[ \left( \frac{\partial f}{\partial q} \right)^2 \frac{\partial^2 f}{\partial p^2} - 2 \frac{\partial f}{\partial p} \frac{\partial f}{\partial q} \frac{\partial^2 f}{\partial p \partial q} + \left( \frac{\partial f}{\partial p} \right)^2 \frac{\partial^2 f}{\partial q^2} \right] \cdot \left( \frac{\partial f}{\partial q} \right)^{-3},$$

<sup>(1)</sup> See  $O_2$ .

<sup>(2)</sup> For some properties of the integral curves, see  $O_1$ .

we must have

$$\begin{aligned} & \left[ \left( \frac{\partial f}{\partial q} \right)^2 \frac{\partial^2 f}{\partial p^2} - 2 \frac{\partial f}{\partial p} \frac{\partial f}{\partial q} \frac{\partial^2 f}{\partial p \partial q} + \left( \frac{\partial f}{\partial p} \right)^2 \frac{\partial^2 f}{\partial q^2} \right] \\ & + \frac{1}{2} \left( \frac{\partial \log \mu}{\partial p} \frac{\partial f}{\partial p} + \frac{\partial \log \mu}{\partial q} \frac{\partial f}{\partial q} \right) \left[ \left( \frac{\partial f}{\partial p} \right)^2 + \left( \frac{\partial f}{\partial q} \right)^2 \right] \\ & + \left( \frac{\partial \log \varphi}{\partial p} \frac{\partial f}{\partial p} + \frac{\partial \log \varphi}{\partial q} \frac{\partial f}{\partial q} \right) \left[ \left( \frac{\partial f}{\partial p} \right)^2 + \left( \frac{\partial f}{\partial q} \right)^2 \right] \\ & + \sqrt{\mu} \psi \cdot \left[ \left( \frac{\partial f}{\partial p} \right)^2 + \left( \frac{\partial f}{\partial q} \right)^2 \right]^{\frac{3}{2}} = 0. \end{aligned}$$

But since the expression of the geodesic curvature  $\frac{1}{\rho_r}$  of  $f = \text{const.}$ :

$$\begin{aligned} -\frac{1}{\rho_r} &= \frac{1}{\mu} \left\{ \frac{\partial}{\partial p} \left( \sqrt{\mu} \frac{\partial f}{\partial p} \left[ \left( \frac{\partial f}{\partial p} \right)^2 + \left( \frac{\partial f}{\partial q} \right)^2 \right]^{-\frac{1}{2}} \right) \right. \\ & \left. + \frac{\partial}{\partial q} \left( \sqrt{\mu} \frac{\partial f}{\partial q} \left[ \left( \frac{\partial f}{\partial p} \right)^2 + \left( \frac{\partial f}{\partial q} \right)^2 \right]^{-\frac{1}{2}} \right) \right\} \end{aligned}$$

gives

$$\begin{aligned} & \left( \frac{\partial f}{\partial q} \right)^2 \frac{\partial^2 f}{\partial p^2} - 2 \frac{\partial f}{\partial p} \frac{\partial f}{\partial q} \frac{\partial^2 f}{\partial p \partial q} + \left( \frac{\partial f}{\partial p} \right)^2 \frac{\partial^2 f}{\partial q^2} \\ & + \frac{1}{2} \left( \frac{\partial \log \mu}{\partial p} \frac{\partial f}{\partial p} + \frac{\partial \log \mu}{\partial q} \frac{\partial f}{\partial q} \right) \\ & = -\frac{\sqrt{\mu}}{\rho_r} \left[ \left( \frac{\partial f}{\partial p} \right)^2 + \left( \frac{\partial f}{\partial q} \right)^2 \right]^{\frac{3}{2}}; \end{aligned}$$

whence we have

$$(6) \quad \frac{1}{\rho_r} - \frac{1}{\sqrt{\mu}} \left( \frac{\partial \log \varphi}{\partial p} \frac{\partial f}{\partial p} + \frac{\partial \log \varphi}{\partial q} \frac{\partial f}{\partial q} \right) \times \left[ \left( \frac{\partial f}{\partial p} \right)^2 + \left( \frac{\partial f}{\partial q} \right)^2 \right]^{-\frac{1}{2}} - \psi = 0.$$

Now consider the differential parameters of the differential quadratic form

$$E du^2 + 2 F du dv + G dv^2:$$

namely

$$A_1 U = \frac{E \left( \frac{\partial U}{\partial v} \right)^2 - 2 F \frac{\partial U}{\partial u} \frac{\partial U}{\partial v} + G \left( \frac{\partial U}{\partial u} \right)^2}{E G - F^2},$$



$$\begin{aligned}
A_2 U &= \frac{1}{\sqrt{EG-F^2}} \left\{ \frac{\partial}{\partial u} \left[ \left( G \frac{\partial U}{\partial u} - F \frac{\partial U}{\partial v} \right) / \sqrt{EG-F^2} \right] \right. \\
&\quad \left. + \frac{\partial}{\partial v} \left[ \left( E \frac{\partial U}{\partial v} - F \frac{\partial U}{\partial u} \right) / \sqrt{EG-F^2} \right] \right\}, \\
r(U, V) &= \frac{E \frac{\partial U}{\partial v} \frac{\partial V}{\partial v} - F \left( \frac{\partial U}{\partial u} \frac{\partial V}{\partial v} + \frac{\partial U}{\partial v} \frac{\partial V}{\partial u} \right) + G \frac{\partial U}{\partial u} \frac{\partial V}{\partial u}}{EG-F^2}.
\end{aligned}$$

If we put

$$\begin{aligned}
u &= p, & v &= q; \\
E &= \mu, & F &= 0, & G &= \mu,
\end{aligned}$$

equation (6) may be written

$$(7) \quad -\frac{1}{\rho_f} + \frac{1}{\sqrt{A_1 f}} r(f, \log \varphi) + \psi = 0,$$

or, by Beltrami's formula,

$$(8) \quad \frac{A_2 f}{\sqrt{A_1 f}} + r\left(f, \frac{1}{\sqrt{A_1 f}}\right) + \frac{1}{\sqrt{A_1 f}} r(f, \log \varphi) + \psi = 0.$$

This is the necessary and sufficient condition that  $f(p, q) = \text{const.}$  should be orbits in the field  $(\varphi, \psi)$  on the surface having the linear element

$$ds^2 = \mu (dp^2 + dq^2).$$

Let us now apply the transformation

$$p = p(u, v), \quad q = q(u, v)$$

and let

$$\mu (dp^2 + dq^2) = E du^2 + 2 F du dv + G dv^2.$$

Putting

$$f(p, q) = \bar{f}(u, v), \quad \varphi(p, q) = \bar{\varphi}(u, v), \quad \psi(p, q) = \bar{\psi}(u, v)$$

and remembering the invariance property of the differential parameters, (8) becomes

$$\frac{A_2 \bar{f}}{\sqrt{A_1 \bar{f}}} + r\left(\bar{f}, \frac{1}{\sqrt{A_1 \bar{f}}}\right) + \frac{1}{\sqrt{A_1 \bar{f}}} r(\bar{f}, \log \bar{\varphi}) + \bar{\psi} = 0.$$

Therefore we have the theorem:

In order that  $\infty^1$  curves

$$f(u, v) = \text{const.}$$

may be orbits in the field  $(\varphi(u, v), \psi(u, v))$  on the surface having the linear element

$$ds^2 = E du^2 + 2 F du dv + G dv^2,$$

it is necessary and sufficient that  $f(u, v)$  should satisfy

$$(8) \quad \frac{A_2 f}{\sqrt{A_1 f}} + r\left(f, \frac{1}{\sqrt{A_1 f}}\right) + \frac{1}{\sqrt{A_1 f}} r(f, \log \varphi) + \psi = 0.$$

2. Let the two surfaces  $S, \bar{S}$  having the linear elements

$$ds^2 = E du^2 + 2 F du dv + G dv^2,$$

$$d\bar{s}^2 = \bar{E} d\bar{u}^2 + 2 \bar{F} d\bar{u} d\bar{v} + \bar{G} d\bar{v}^2$$

be related by the conformal representation such that

$$\frac{\bar{E}}{E} = \frac{\bar{F}}{F} = \frac{\bar{G}}{G} = \varphi^2(u, v).$$

Then the differential parameters corresponding to the surface  $\bar{S}$  have the expressions:

$$\bar{A}_1 f = \frac{1}{\varphi^2} A_1 f, \quad \bar{A}_2 f = \frac{1}{\varphi^2} A_2 f,$$

$$\begin{aligned}
\bar{r}\left(f, \frac{1}{\sqrt{A_1 f}}\right) &= \bar{r}\left(f, \frac{\varphi}{\sqrt{A_1 f}}\right) \\
&= \varphi \cdot \bar{r}\left(f, \frac{1}{\sqrt{A_1 f}}\right) + \frac{1}{\sqrt{A_1 f}} \cdot \bar{r}(f, \varphi) \\
&= \frac{1}{\varphi} \cdot r\left(f, \frac{1}{\sqrt{A_1 f}}\right) + \frac{1}{\varphi \sqrt{A_1 f}} r(f, \log \varphi);
\end{aligned}$$

so that (8) may be written

$$(9) \quad \frac{\bar{A}_2 f}{\sqrt{A_1 f}} \bar{r} + \left(f, \frac{1}{\sqrt{A_1 f}}\right) + \frac{\psi}{\varphi} = 0.$$

Consequently if  $\frac{1}{\rho_f}$  be the geodesic curvature of  $f = \text{const.}$  on the surface  $\bar{S}$ , we have



$$(10) \quad \frac{1}{\bar{\rho}_f} = \frac{\phi}{\varphi}.$$

Thus we arrive at the theorem:

By the conformal representation

$$d\bar{s}^2 = \varphi^2 ds^2,$$

the orbits  $f = \text{const.}$  in the field  $(\varphi, \phi)$  on the surface  $S$  are transformed into the curves having the geodesic curvature

$$\frac{1}{\bar{\rho}_f} = \frac{\phi}{\varphi}$$

on the surface  $\bar{S}$ ; and conversely.

In the particular case where  $\varphi = \text{const.}$ , we have from (7)

$$\frac{1}{\rho_f} = \phi.$$

On the other hand, in the reversible field (that is, the case where  $\phi = 0$  identically), we have from (10)

$$\frac{1}{\bar{\rho}_f} = 0;$$

so that  $f = \text{const.}$  are geodesics on the surface  $\bar{S}$ , which is a well known result <sup>(1)</sup>.

### The condition for $2\infty^1$ given orbits.

3. Now we can infer from (8) the theorem immediately:

The necessary and sufficient condition that the  $2\infty^1$  curves  $u = \text{const.}$ ,  $v = \text{const.}$  may be orbits in the field  $(\varphi, \phi)$  on the surface  $S$  is given by

$$(11) \quad G \frac{\partial \log \varphi}{\partial u} - F \frac{\partial \log \varphi}{\partial v} = \frac{EG - F^2}{G} \begin{Bmatrix} 2 & 2 \\ 1 & 1 \end{Bmatrix} - \sqrt{G} \sqrt{EG - F^2} \phi,$$

$$(12) \quad -F \frac{\partial \log \varphi}{\partial u} + E \frac{\partial \log \varphi}{\partial v} = \frac{EG - F^2}{E} \begin{Bmatrix} 11 \\ 2 & 2 \end{Bmatrix} - \sqrt{E} \sqrt{EG - F^2} \phi^{(2)},$$

<sup>(1)</sup> Darboux, *Théorie des surfaces*, 2 (1 éd., 1889), p. 453; See also  $O_3$ , p. 173.

<sup>(2)</sup> In the reversible field  $\phi$  vanishes identically; so (11) and (12) become

$$G \frac{\partial \log \varphi}{\partial u} - F \frac{\partial \log \varphi}{\partial v} = \frac{EG - F^2}{G} \begin{Bmatrix} 22 \\ 1 & 1 \end{Bmatrix},$$

$$-F \frac{\partial \log \varphi}{\partial u} + E \frac{\partial \log \varphi}{\partial v} = \frac{EG - F^2}{E} \begin{Bmatrix} 11 \\ 2 & 2 \end{Bmatrix}$$

respectively. Compare with  $O_3$  p. 179.

where  $\begin{Bmatrix} 11 \\ 2 & 2 \end{Bmatrix}$ ,  $\begin{Bmatrix} 22 \\ 1 & 1 \end{Bmatrix}$  denote Christoffel's symbols, that is,

$$\begin{Bmatrix} 11 \\ 2 & 2 \end{Bmatrix} = \frac{-F \frac{\partial E}{\partial u} - E \frac{\partial E}{\partial v} + 2E \frac{\partial F}{\partial u}}{2(EG - F^2)},$$

$$\begin{Bmatrix} 22 \\ 1 & 1 \end{Bmatrix} = \frac{-F \frac{\partial G}{\partial v} - G \frac{\partial G}{\partial u} + 2G \frac{\partial F}{\partial v}}{2(EG - F^2)}.$$

In order to interpret this condition geometrically, let us apply the conformal representation such that

$$d\bar{s}^2 = \varphi^2 ds^2.$$

Then (11) and (12) are equivalent to

$$\frac{1}{\bar{\rho}_u} = \frac{\phi}{\varphi}, \quad \frac{1}{\bar{\rho}_v} = \frac{\phi}{\varphi}$$

respectively (§2); from which we find

$$(13) \quad \frac{1}{\bar{\rho}_u} = \frac{1}{\bar{\rho}_v}.$$

Conversely, consider the parametric curves  $u, v$  on a surface  $S$ , such that

$$\frac{1}{\bar{\rho}_u} = \frac{1}{\bar{\rho}_v} (= \Phi(u, v), \text{ say}).$$

Take any function  $\varphi(u, v)$  and put  $\phi = \varphi \Phi$ . Then  $u, v$  will be orbits in the field  $(\varphi, \phi)$  on the surface  $S$ , which is obtained from  $\bar{S}$  by the conformal transformation

$$\frac{1}{\varphi^2} d\bar{s}^2 = ds^2.$$

Thus we have the theorem:

In order that  $2\infty^1$  curves  $u, v$  may be orbits on a surface  $S$  in an irreversible field of force, it is necessary and sufficient that the corresponding curves on the surface  $\bar{S}$ , obtained from  $S$  by a certain conformal transformation, should have the property

$$\frac{1}{\bar{\rho}_u} = \frac{1}{\bar{\rho}_v}.$$

4. Since (11), (12) may be written



$$(14) \quad \frac{1}{\sqrt{EG-F^2}} \left[ \sqrt{G} \frac{\partial \log \varphi}{\partial u} - \frac{F}{\sqrt{G}} \frac{\partial \log \varphi}{\partial v} \right] = \frac{1}{\rho_u} - \phi,$$

$$(15) \quad \frac{1}{\sqrt{EG-F^2}} \left[ -\frac{F}{\sqrt{E}} \frac{\partial \log \varphi}{\partial u} + \sqrt{E} \frac{\partial \log \varphi}{\partial v} \right] = \frac{1}{\rho_v} - \phi$$

respectively, if we put

$$F_u = \frac{\varphi^2}{\sqrt{G}} \frac{\partial \log \varphi}{\partial v}, \quad F_v = \frac{\varphi^2}{\sqrt{E}} \frac{\partial \log \varphi}{\partial u},$$

$$F_w = \frac{\varphi^2}{\rho_u} - \varphi^2 \phi, \quad F_v = \frac{\varphi^2}{\rho_v} - \varphi^2 \phi.$$

we can derive the two equations:

$$(16) \quad F_u \cos \frac{\omega}{2} + F_w \sin \frac{\omega}{2} = F_v \cos \frac{\omega}{2} + F_v' \sin \frac{\omega}{2},$$

$$(17) \quad F_u \sin \frac{\omega}{2} - F_w \cos \frac{\omega}{2} = -F_v \sin \frac{\omega}{2} + F_v' \cos \frac{\omega}{2},$$

$\omega$  being the angle between  $u=\text{const.}$  and  $v=\text{const.}$

Now denote by  $\mathfrak{F}_u$  the vector having  $F_u$  as its magnitude and the (positive) direction of the curve  $u=\text{const.}$  as its direction, and by  $\mathfrak{F}_w$  the vector having  $F_w$  as its magnitude and the direction to the centre of geodesic curvature of  $u=\text{const.}$  as its direction; also define  $\mathfrak{F}_v$  and  $\mathfrak{F}_{v'}$  in similar ways with respect to  $v=\text{const.}$ . Then it follows from (16) and (17) that the projections of the resultant of  $\mathfrak{F}_u$  and  $\mathfrak{F}_w$  upon the two bisectors of the angles (internal and external) between  $u=\text{const.}$ ,  $v=\text{const.}$  are equal to those for  $\mathfrak{F}_v$  and  $\mathfrak{F}_{v'}$  upon the same bisectors respectively.

Consequently we arrive at the *dynamical interpretation* of the conditions (11) and (12):

A necessary and sufficient condition that  $u=\text{const.}$  and  $v=\text{const.}$  may be orbits in the field  $(\varphi, \phi)$  is that the resultant of the two vectors  $\mathfrak{F}_u$  and  $\mathfrak{F}_w$  is equal to the resultant of  $\mathfrak{F}_v$  and  $\mathfrak{F}_{v'}$ .<sup>(1)</sup>

In the reversible field ( $\phi=0$ ), if  $\mathfrak{F}_{u0}$  ( $\mathfrak{F}_{v0}$ ) and  $\mathfrak{F}_{u'0}$  ( $\mathfrak{F}_{v'0}$ ) be the components of force tangential and normal to the orbit  $u=\text{const.}$  ( $v=\text{const.}$ ) respectively, we have the well known relations:

$$F_{u0} = \frac{\varphi^2}{\sqrt{G}} \frac{\partial \log \varphi}{\partial v}, \quad F_{v0} = \frac{\varphi^2}{\sqrt{E}} \frac{\partial \log \varphi}{\partial u},$$

<sup>(1)</sup> Compare with O<sub>4</sub>, p. 140.

$$F_{u'0} = \frac{\varphi^2}{\rho_u}, \quad F_{v'0} = \frac{\varphi^2}{\rho_v}.$$

5. In this paragraph I will give three pairs of the formulae concerning the geodesic curvatures of 2  $\infty^1$  orbits  $u=\text{const.}$ ,  $v=\text{const.}$  and their related curves.

I. Let  $ds(u_1)$  and  $ds(v_1)$  be the arc elements of the curves  $u_1=\text{const.}$  and  $v_1=\text{const.}$  which are the bisectors of the angles, external, between  $u=\text{const.}$  and  $v=\text{const.}$  respectively. Then

$$(18) \quad \begin{cases} 2 \sin \frac{\omega}{2} \cdot \frac{\partial}{\partial s(u_1)} (\log \varphi) = \frac{1}{\sqrt{E}} \frac{\partial}{\partial u} (\log \varphi) - \frac{1}{\sqrt{G}} \frac{\partial}{\partial v} (\log \varphi), \\ 2 \cos \frac{\omega}{2} \cdot \frac{\partial}{\partial s(v_1)} (\log \varphi) = \frac{1}{\sqrt{E}} \frac{\partial}{\partial u} (\log \varphi) + \frac{1}{\sqrt{G}} \frac{\partial}{\partial v} (\log \varphi). \end{cases}$$

Therefore by means of (18) we find from (14) and (15) the following formulae of importance:

$$(19) \quad \begin{cases} \cos \frac{\omega}{2} \cdot \frac{\partial}{\partial s(u_1)} (\log \varphi) = \frac{1}{2} \left( \frac{1}{\rho_u} - \frac{1}{\rho_v} \right), \\ \sin \frac{\omega}{2} \cdot \frac{\partial}{\partial s(v_1)} (\log \varphi) = \frac{1}{2} \left( \frac{1}{\rho_u} + \frac{1}{\rho_v} \right) - \phi. \end{cases}$$

II. Next suppose that  $u'=\text{const.}$ ,  $v'=\text{const.}$  are the orthogonal trajectories of  $u=\text{const.}$ ,  $v=\text{const.}$  respectively. Then we have

$$(20) \quad \begin{cases} \frac{G}{E} \left\{ \begin{smallmatrix} 11 \\ 2 \end{smallmatrix} \right\} + \frac{F}{G} \left\{ \begin{smallmatrix} 22 \\ 1 \end{smallmatrix} \right\} = \frac{\sqrt{G}}{\rho_w} - \frac{G}{\sqrt{EG-F^2}} \frac{\partial \omega}{\partial u}, \\ \frac{F}{E} \left\{ \begin{smallmatrix} 11 \\ 2 \end{smallmatrix} \right\} + \frac{E}{G} \left\{ \begin{smallmatrix} 22 \\ 1 \end{smallmatrix} \right\} = \frac{\sqrt{E}}{\rho_{v'}} - \frac{E}{\sqrt{EG-F^2}} \frac{\partial \omega}{\partial v} \quad (1). \end{cases}$$

Now from (11), (12) and (20) we get

$$\begin{aligned} \frac{1}{\sqrt{G}} \frac{\partial \log \varphi}{\partial v} &= \frac{1}{\rho_w} - \frac{\sqrt{G}}{\sqrt{EG-F^2}} \frac{\partial \omega}{\partial u} - \frac{\sqrt{EG+F^2}}{\sqrt{EG-F^2}} \phi, \\ \frac{1}{\sqrt{E}} \frac{\partial \log \varphi}{\partial u} &= \frac{1}{\rho_{v'}} - \frac{\sqrt{E}}{\sqrt{EG-F^2}} \frac{\partial \omega}{\partial v} - \frac{\sqrt{EG+F^2}}{\sqrt{EG-F^2}} \phi. \end{aligned}$$

Applying (18) to these two equations we find the formulae:

<sup>(1)</sup> For an application of these formulae, see Ogura, "On a generalization of the Bonnet-Darboux theorem concerning the line of striction," Proc. Tōkyō Math.-Phys. Soc., II, 9 (1918), p. 304; where these formulae have been printed incorrectly.



$$(21) \begin{cases} \sin \frac{\omega}{2} \cdot \frac{\partial}{\partial s(u_1)} (\log \varphi) - \frac{1}{2} \sec \frac{\omega}{2} \cdot \frac{\partial \omega}{\partial s(u_1)} = -\frac{1}{2} \left( \frac{1}{\rho_{u'}} - \frac{1}{\rho_{v'}} \right), \\ \cos \frac{\omega}{2} \cdot \frac{\partial}{\partial s(v_1)} (\log \varphi) + \frac{1}{2} \operatorname{cosec} \frac{\omega}{2} \cdot \frac{\partial \omega}{\partial s(v_1)} = \frac{1}{2} \left( \frac{1}{\rho_{u'}} + \frac{1}{\rho_{v'}} \right) \\ - \cot \frac{\omega}{2} \cdot \psi. \end{cases}$$

III. Lastly applying the following formulae of Prof. Lilienthal<sup>(1)</sup>

$$\begin{aligned} \frac{2}{\rho(u_1)} &= \sin \frac{\omega}{2} \cdot \left( \frac{1}{\rho_u} + \frac{1}{\rho_v} \right) + \cos \frac{\omega}{2} \cdot \left( \frac{1}{\rho_{u'}} + \frac{1}{\rho_{v'}} \right), \\ \frac{2}{\rho(v_1)} &= -\cos \frac{\omega}{2} \cdot \left( \frac{1}{\rho_u} - \frac{1}{\rho_v} \right) + \sin \frac{\omega}{2} \cdot \left( \frac{1}{\rho_{u'}} - \frac{1}{\rho_{v'}} \right) \end{aligned}$$

to (19) and (21), we obtain the formulae:

$$(22) \begin{cases} \frac{\partial}{\partial s(u_1)} (\log \varphi) - \frac{1}{2} \cot \frac{\omega}{2} \cdot \frac{\partial \omega}{\partial s(u_1)} = -\frac{1}{\rho(v_1)}, \\ \frac{\partial}{\partial s(v_1)} (\log \varphi) + \frac{1}{2} \cot \frac{\omega}{2} \cdot \frac{\partial \omega}{\partial s(v_1)} = \frac{1}{\rho(u_1)} - \operatorname{cosec} \frac{\omega}{2} \cdot \psi. \end{cases}$$

## PART II. Some Particular Cases.

### 2 $\infty^1$ orbits comprising a constant angle.

6. Hereafter we will consider some system of 2  $\infty^1$  orbits in the field  $(\varphi, \psi)$ , which are of geometrical interest.

We begin with the case where the angle  $\omega$  between  $u=\text{const.}$ ,  $v=\text{const.}$  is constant.

In this case (19), (21) and (22) give

$$\begin{aligned} \cos \frac{\omega}{2} \cdot \frac{\partial}{\partial s(u_1)} (\log \varphi) &= \frac{1}{2} \left( \frac{1}{\rho_u} - \frac{1}{\rho_v} \right), \\ \sin \frac{\omega}{2} \cdot \frac{\partial}{\partial s(u_1)} (\log \varphi) &= -\frac{1}{2} \left( \frac{1}{\rho_{u'}} - \frac{1}{\rho_{v'}} \right), \\ \frac{\partial}{\partial s(u_1)} (\log \varphi) &= -\frac{1}{\rho(v_1)}; \end{aligned}$$

so that we find

<sup>(1)</sup> Lilienthal, Vorlesungen über Differentialgeometrie, II<sub>1</sub> (1913), pp. 240-241.

$$(23) \quad \frac{2 \cos \frac{\omega}{2}}{\rho(v_1)} = -\left( \frac{1}{\rho_u} - \frac{1}{\rho_v} \right),$$

$$(24) \quad \frac{2 \sin \frac{\omega}{2}}{\rho(v_1)} = \frac{1}{\rho_{u'}} - \frac{1}{\rho_{v'}}.$$

Similarly

$$(25) \quad \frac{2 \sin \frac{\omega}{2}}{\rho(u_1)} = \frac{1}{\rho_u} + \frac{1}{\rho_v},$$

$$(26) \quad \frac{2 \cos \frac{\omega}{2}}{\rho(u_1)} = \frac{1}{\rho_{u'}} + \frac{1}{\rho_{v'}} \quad (^1).$$

Since the product of the right hand sides of (23) and (25) is equal to that for (24) and (26), we have

$$\frac{1}{\rho_u^2} + \frac{1}{\rho_{u'}^2} = \frac{1}{\rho_v^2} + \frac{1}{\rho_{v'}^2}.$$

Adding the squares of (23), (24), (25) and (26),

$$2 \left( \frac{1}{\rho^2(u_1)} + \frac{1}{\rho^2(v_1)} \right) = \frac{1}{\rho_u^2} + \frac{1}{\rho_v^2} + \frac{1}{\rho_{u'}^2} + \frac{1}{\rho_{v'}^2}.$$

From the last two equations we obtain

$$\frac{1}{\rho^2(u_1)} + \frac{1}{\rho^2(v_1)} = \frac{1}{\rho_u^2} + \frac{1}{\rho_{u'}^2} = \frac{1}{\rho_v^2} + \frac{1}{\rho_{v'}^2}.$$

7. As a simple application, let us consider the 2  $\infty^1$  curves  $u, v$  which make a constant angle and may be orbits in the irreversible field determined by

<sup>(1)</sup> These four formulae have certain similarities with the following four concerning a net of curves without ambages  $\bar{u}=\text{const.}$ ,  $\bar{v}=\text{const.}$ :

$$\begin{aligned} \frac{4 \cos \frac{\varpi}{2}}{\rho(\bar{v}_1)} &= -\left( \frac{1}{\rho \bar{u}} - \frac{1}{\rho \bar{v}} \right), & \frac{2 \cos \frac{\varpi}{2}}{\rho(\bar{v}_1)} &= -\sin \frac{\varpi}{2} \cdot \left( \frac{1}{\rho \bar{u}'} - \frac{1}{\rho \bar{v}'} \right), \\ \frac{4 \sin \frac{\varpi}{2}}{\rho(\bar{u}_1)} &= \frac{1}{\rho \bar{u}} + \frac{1}{\rho \bar{v}}, & \frac{2 \cos \frac{\varpi}{2}}{\rho(\bar{u}_1)} &= \cos \frac{\varpi}{2} \cdot \left( \frac{1}{\rho \bar{u}'} + \frac{1}{\rho \bar{v}'} \right), \end{aligned}$$

$\varpi$  being the angle between  $\bar{u}$  and  $\bar{v}$ . See Lilienthal, loc. cit., pp. 244-245.



$$\varphi = \text{const.}, \psi = \text{const.}$$

From (19) we have

$$\frac{1}{\rho_u} = \frac{1}{\rho_v} = \text{const.} (=k, \text{ say});$$

so that from (23) and (25)

$$\frac{1}{\rho(v_1)} = 0, \quad \frac{1}{\rho(u_1)} = \frac{k}{\sin \frac{\omega}{2}} = \text{const.}$$

Consequently by well known theorems the surface must be a pseudospherical surface of revolution of the parabolic type or a surface applicable to it, and  $u = \text{const.}$ ,  $v = \text{const.}$  make constant angles ( $\frac{\omega}{2}$  and  $-\frac{\omega}{2}$  respectively) with the geodesic parallels  $u_1 = \text{const.}$ . Conversely if a surface have the linear element

$$ds^2 = du_1^2 + c^2 e^{\frac{2u_1}{a}} dv_1^2,$$

$a, c$  being constants, we have

$$\frac{1}{\rho(v_1)} = 0, \quad \frac{1}{\rho(u_1)} = \frac{1}{a}.$$

Hence equations (22) are satisfied by

$$\omega = \text{const.}, \varphi = \text{const.}, \psi = \text{const.}, \text{ where } \operatorname{cosec} \frac{\omega}{2} \cdot \psi = \frac{1}{a}.$$

Therefore in order that the  $2 \infty^1$  curves  $u = \text{const.}$ ,  $v = \text{const.}$  which make a constant angle and may be orbits in an irreversible field of the form ( $\varphi = \text{const.}$ ,  $\psi = \text{const.}$ ), it is necessary and sufficient that the surface should be a pseudospherical surface of revolution of the parabolic type or a surface applicable to it, and moreover the bisectors of the external angles of  $u, v$  should be geodesic parallels.

### The isothermal system as orbits.

8. For the reversible field of force (i. e.  $\psi = 0$  identically), I have proved the theorem <sup>(1)</sup>: A necessary and sufficient condition that  $2 \infty^1$  curves belonging to an orthogonal system may be orbits in a reversible

field of force is that these curves form an isothermal system. Now I proceed to establish the following theorem concerning the irreversible field of force ( $\varphi, \psi$ ):

Consider an orthogonal system  $u = \text{const.}$ ,  $v = \text{const.}$ . If any three of the four propositions be true:

- (i) that  $u, v$  form an isothermal system;
- (ii) that  $u, v$  form a net of curves without ambages;
- (iii) that  $\psi$  is constant along each bisector  $u_1 = \text{const.}$  of the external angles of  $u, v$ ;
- (iv) that  $u, v$  may be orbits in the field of the form ( $\varphi, \psi$ ); then the fourth is true also.

In virtue of  $F = 0$ , the necessary and sufficient conditions for (i), (ii), (iii), (iv) are given by

$$(i) \quad \frac{\partial^2 \log E}{\partial u \partial v} = \frac{\partial^2 \log G}{\partial u \partial v};$$

$$(ii) \quad \frac{\partial \sqrt{E}}{\partial v} = \frac{\partial \sqrt{G}}{\partial u} \quad (1);$$

$$(iii) \quad \sqrt{G} \frac{\partial \psi}{\partial u} = \sqrt{E} \frac{\partial \psi}{\partial v};$$

$$(iv) \quad \begin{cases} \frac{\partial \log \varphi}{\partial u} = -\frac{1}{2} \frac{\partial \log G}{\partial u} - \sqrt{E} \cdot \psi, \\ \frac{\partial \log \varphi}{\partial v} = -\frac{1}{2} \frac{\partial \log E}{\partial v} - \sqrt{G} \cdot \psi \end{cases}$$

respectively.

Firstly suppose that (i), (ii), (iii) are true. Then we have

$$\begin{aligned} & \frac{1}{2} \frac{\partial^2 \log G}{\partial u \partial v} + \psi \frac{\partial \sqrt{E}}{\partial v} + \sqrt{E} \frac{\partial \psi}{\partial v} \\ &= \frac{1}{2} \frac{\partial^2 \log E}{\partial u \partial v} + \psi \frac{\partial \sqrt{G}}{\partial u} + \sqrt{G} \frac{\partial \psi}{\partial u}, \end{aligned}$$

which shows us that

$$\left( \frac{1}{2} \frac{\partial \log G}{\partial u} + \sqrt{E} \cdot \psi \right) du + \left( \frac{1}{2} \frac{\partial \log E}{\partial v} + \sqrt{G} \cdot \psi \right) dv$$

<sup>(1)</sup> See, for example, R. Rothe, "Bemerkungen über die Gewebe (Kurvennetze ohne Umwege) auf einer Fläche," Jahresb. Deuts. Math. Ver., 17 (1903), p. 325.

<sup>(1)</sup> O<sub>1</sub>, p. 168, p. 173, p. 180.



is an exact differential. Hence if we define the function  $\varphi$  by

$$\log \varphi = -\int \left( \frac{1}{2} \frac{\partial \log G}{\partial u} + \sqrt{E} \cdot \phi \right) du + \left( \frac{1}{2} \frac{\partial \log E}{\partial v} + \sqrt{G} \cdot \psi \right) dv,$$

equations (iv) are satisfied; that is,  $u, v$  may be orbits in the field  $(\varphi, \psi)$ .

Next suppose that (i), (iii), (iv) are true. Then (iv) gives the condition of integrability

$$\begin{aligned} & \frac{1}{2} \frac{\partial^2 \log G}{\partial u \partial v} + \phi \frac{\partial \sqrt{E}}{\partial v} + \sqrt{E} \frac{\partial \phi}{\partial v} \\ &= \frac{1}{2} \frac{\partial^2 \log E}{\partial u \partial v} + \psi \frac{\partial \sqrt{G}}{\partial u} + \sqrt{G} \frac{\partial \psi}{\partial u}, \end{aligned}$$

from which we find, by means of (i) and (iii)

$$\frac{\partial \sqrt{E}}{\partial v} = \frac{\partial \sqrt{G}}{\partial u}.$$

In similar ways we can prove other two cases.

### The striped net of curves without ambages as orbits.

9. It is well known that  $2 \infty^1$  geodesics  $u, v$  may be orbits in a reversible field when and only when  $\varphi$  is constant<sup>(1)</sup>. A generalization of this can be obtained from (19) immediately:

If  $2 \infty^1$  curves  $u = \text{const.}, v = \text{const.}$  such that

$$\frac{1}{\rho_u} = \frac{1}{\rho_v}$$

may be orbits in an irreversible field, the function  $\varphi$  must be constant along  $u_1 = \text{const.}$ . When the condition is fulfilled,  $\phi$  is determined by

$$\phi = \frac{1}{\rho} - \sin \frac{\omega}{2} \cdot \frac{\partial}{\partial s(v_1)} (\log \varphi),$$

where we have put

$$\frac{1}{\rho} = \frac{1}{\rho_u} = \frac{1}{\rho_v}.$$

Already I have dealt with the condition that a striped net of curves

without ambages should be orbits in a reversible field<sup>(1)</sup>. Now we can prove the theorem:

Let  $u = \text{const.}, v = \text{const.}$  be a striped net of curves without ambages.

If any two of the three propositions be true:

(i) that each of  $u_1 = \text{const.}$  has a constant geodesic curvature;

(ii) that  $\phi$  is constant along  $u_1 = \text{const.}$ ;

(iii) that  $u, v$  may be orbits in the field of the form  $(\varphi, \psi)$ ;

then the third is true also; and  $\varphi$  is constant along  $u_1 = \text{const.}$

I. Firstly we will deduce (iii) from (i) and (ii). Since  $u, v$  form a striped net of curves without ambages, we may take

$$(27) \quad E = \left( \frac{\partial u_1}{\partial u} \right)^2, \quad F = \frac{\partial u_1}{\partial u} \frac{\partial u_1}{\partial v} \cos \omega, \quad G = \left( \frac{\partial u_1}{\partial v} \right)^2,$$

where  $\omega$  is a function of  $u_1$  alone and  $u_1 = \text{const.}$  are the bisectors of the external angles between  $u$  and  $v$ <sup>(2)</sup>. Moreover we have

$$(28) \quad \rho_u = \rho_v (= \rho, \text{ say})^{(3)}.$$

But I have proved the following lemma<sup>(4)</sup>: When  $u, v$  form a striped net of curves without ambages, each of  $u_1 = \text{const.}$  has a constant geodesic curvature  $\frac{1}{\rho(u_1)}$  when and only when  $\rho$  is constant along  $u_1 = \text{const.}$

Hence it follows from (i) that  $\rho$  is a function of  $u_1$  only. Moreover we see from (ii) that  $\phi$  is also a function of  $u_1$  only. If we define the function  $\varphi$  by

$$\log \varphi = \int \cot \frac{\omega}{2} \cdot \left( \frac{1}{\rho} - \phi \right) du_1,$$

then

$$\frac{\partial \log \varphi}{\partial u} = \cot \frac{\omega}{2} \cdot \left( \frac{1}{\rho} - \phi \right) \frac{\partial u_1}{\partial u},$$

$$\frac{\partial \log \varphi}{\partial v} = \cot \frac{\omega}{2} \cdot \left( \frac{1}{\rho} - \phi \right) \frac{\partial u_1}{\partial v}.$$

Consequently we have from (27), (28) and the last two equations

$$(14) \quad \frac{1}{\sqrt{EG} - F^2} \left[ \sqrt{G} \frac{\partial \log \varphi}{\partial u} - \frac{F}{\sqrt{G}} \frac{\partial \log \varphi}{\partial v} \right] = \frac{1}{\rho_u} - \phi,$$

(<sup>1</sup>) O<sub>5</sub>, pp. 284-286; consult with O<sub>6</sub> also.

(<sup>2</sup>), (<sup>3</sup>) Rothe, loc. cit.

(<sup>4</sup>) See O<sub>6</sub>.

(<sup>1</sup>) O<sub>3</sub>, p. 133, p. 181.



$$(15) \quad \frac{1}{\sqrt{EG-F^2}} \left[ -\frac{F}{\sqrt{E}} \frac{\partial \log \varphi}{\partial u} + \sqrt{E} \frac{\partial \log \varphi}{\partial v} \right] = \frac{1}{\rho_v} - \phi.$$

Thus the proposition (iii) has been obtained.

II. Next we will deduce (ii) from (i) and (iii). Since  $u, v$  form a striped net of curves without ambages, (28) must hold. Hence in order that (iii) is true, by the first theorem in this paragraph,  $\varphi$  must be a function of  $u_1$  only. But from (27) and (iii) we have

$$\begin{aligned} \frac{1}{\sqrt{EG-F^2}} \left[ \sqrt{G} \frac{\partial \log \varphi}{\partial u} - \frac{F}{\sqrt{G}} \frac{\partial \log \varphi}{\partial v} \right] &= \operatorname{tg} \frac{\omega(u_1)}{2} \cdot \frac{d}{du_1} \log \varphi(u_1) \\ &= \frac{1}{\rho} - \phi. \end{aligned}$$

Moreover we see from (i) and the lemma above mentioned that  $\rho$  is a function of  $u_1$  only; so that  $\phi$  must be a function of  $u_1$  only.

III. Lastly we will deduce (i) from (ii) and (iii). From (iii) we get

$$\operatorname{tg} \frac{\omega(u_1)}{2} \cdot \frac{1}{du_1} \log \varphi(u_1) = \frac{1}{\rho} - \phi.$$

But by (ii)  $\phi$  is a function of  $u_1$  only; so that  $\rho$  must be a function of  $u_1$  alone. Therefore by the above lemma, each of  $u_1 = \text{const.}$  has a constant geodesic curvature.

10. Now we see, from the last theorem, that if a striped net of curves without ambages  $u = \text{const.}, v = \text{const.}$  may be orbits in the field  $(\varphi, \phi(u_1))$ , then each of  $u_1 = \text{const.}$  should have a constant geodesic curvature. On the other hand, since  $u, v$  form a striped net of curves without ambages,  $u_1 = \text{const.}$  are geodesic parallels<sup>(1)</sup>. Hence it follows that the linear element must take the form

$$ds^2 = du_1^2 + U_1(u_1) dv_1^2,$$

$U_1(u_1)$  being a function of  $u_1$  alone; and the surface should be applicable to a surface of revolution.

Conversely, if a surface be applicable to a surface of revolution and  $u, v$  form a striped net of curves without ambages, then we must have

$$\begin{aligned} ds^2 &= \sec^2 \frac{\omega}{2} du_1^2 + \mu^2 \sin^2 \frac{\omega}{2} dv_1^2 \\ &= \sec^2 \frac{\omega}{2} du_1^2 + f_1(u_1) f_2(v_1) dv_1^2, \end{aligned}$$

(<sup>1</sup>) Rothe, loc. cit.

where  $\omega$  and  $f_1(u_1)$  are functions of  $u_1$  alone and  $f_2(v_1)$  of  $v_1$  alone; so that  $\mu$  takes the form  $F_1(u_1) F_2(v_1)$ . But in virtue of the formula

$$-\frac{2}{\rho(u_1)} = \sin \omega \cdot \frac{\partial}{\partial u_1} \log \left( \mu \sin^2 \frac{\omega}{2} \right)^{(\dagger)}$$

$\rho(u_1)$  should be a function of  $u_1$  alone. Therefore, by the last theorem,  $u, v$  may be orbits in the field of the form  $(\varphi, \phi(u_1))$ . Thus we have theorem:

*In order that a surface may have a striped net of curves without ambages  $u, v$  which can be orbits in the field  $(\varphi, \phi(u_1))$ , it is necessary and sufficient that the surface should be applicable to a surface of revolution.*

Moreover we can state the following theorem<sup>(2)</sup>:

*In order that  $u, v$  constitute a striped net of curves without ambages which can be orbits in the field of the form  $(\varphi, \phi(u_1))$ , it is necessary and sufficient that the linear element should take the form*

$$ds^2 = \hat{\xi}(u+v) \left[ du^2 + 2\eta(u+v) du dv + dv^2 \right],$$

where  $\hat{\xi}$  and  $\eta$  are functions of  $u+v$  only.

Lastly we add the theorem:

*If a striped net of curves without ambages  $u, v$  be orbits in the reversible field  $(\varphi, 0)$ , then the net may be orbits in the irreversible field of the form  $(\varphi, \phi(u_1))$  also.*

Ikeda near Ôsaka, June 1918.

(<sup>1</sup>) Rothe, loc. cit.

(<sup>2</sup>) For the method of proof, see O<sub>5</sub>, pp. 287-288.



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